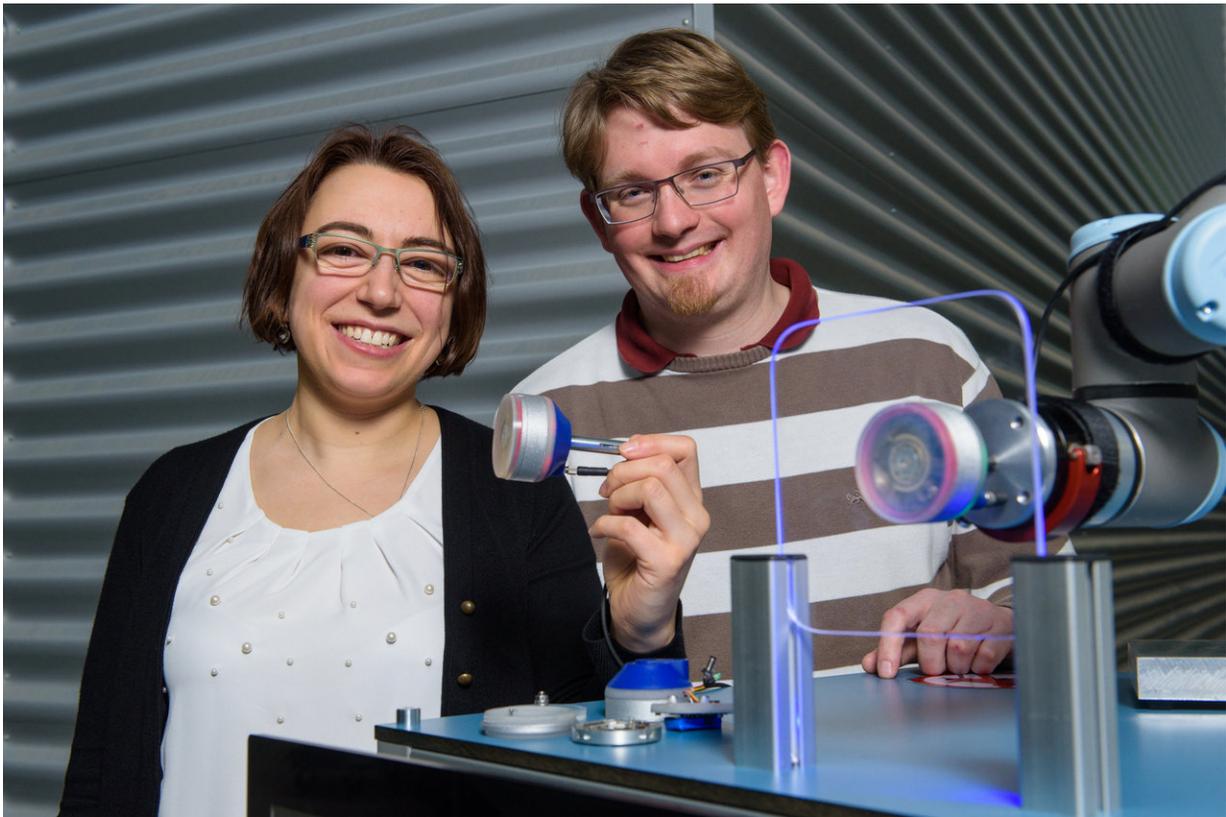


# Robot-mounted vacuum grippers flex their artificial muscles

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Susanne-Marie Kirsch and her research colleague Felix Welsch (r.) are research assistants within the group led by Stefan Seelecke and are developing and optimizing the vacuum gripper technology. Credit: Oliver Dietze

A short electric pulse is all it takes to generate and release a powerful

vacuum in the blink of an eye. The novel vacuum gripper developed by the research team led by Professor Stefan Seelecke at Saarland University enables robot arms to pick up objects and move them around freely in space. The system works without the need for compressed air to generate the vacuum, it is energy efficient, quiet and suitable for use in clean rooms. The specialists for intelligent materials systems make use of artificial muscles, which are bundles of ultrafine shape memory wires that are able to tense and relax just as real muscle fibres do. The wires also function as sensors and can sense, for example, when the gripper needs to readjust or tighten its grip.

Vacuum grippers are commonly used in industrial production lines, where they are used to sort, convey and hold smooth and relatively flat objects so that screws can be driven in, surfaces painted or components assembled. Using vacuum grippers is typically a noisy affair. The most common systems use compressed air, which not only makes them loud, but also means they need heavy ancillary equipment, which drives up costs and makes the entire system somewhat inflexible. They also consume significant amounts of energy.

The situation is quite different in the case of the new vacuum technology that has been developed by Professor Stefan Seelecke of Saarland University and the Center for Mechatronics and Automation Technology in Saarbrücken (ZeMA). The shape-memory vacuum [gripper](#) can produce a powerful vacuum using nothing more than a robot arm to guide it into position. It does not require any additional electric or pneumatic drive system, it is light, adaptable, cost-effective to produce, and noiseless. It requires only small pulses of electric current, one pulse to generate the vacuum and one to release it. No additional electric power is required while the gripper is holding an object, even if the object has to be gripped for a long time or if it has to be held at an angle.

The technology is based on the shape memory properties of nickel-

titanium alloy. "Shape memory refers to the fact that a material is able to change its shape and return to its original shape after it has been deformed. If electric current flows through a [wire](#) made from this alloy, the wire becomes warmer and its lattice structure transforms in such a way that the wire shortens in length. If the current ceases, the wire cools down and lengthens again," says Stefan Seelecke, explaining the key underlying material phase transitions. The ultrafine wires therefore contract and relax like muscle fibres, depending on whether an electric current is flowing or not. "These shape memory wires have the highest energy density of all known drive mechanisms, which enables them to perform powerful movements in restricted spaces," explains Seelecke.

To construct a vacuum gripper, the researchers arranged bundles of these fibres in the manner analogous to a circular muscle around a thin metal disc that can flip up or down, like a frog clicker toy. Applying an electrical pulse makes the wires contract and the disc flips position. The disc is attached to a rubber membrane on a flat smooth surface. When the disc flips position, it pulls on the membrane, creating a strong, stable vacuum. By bundling the wires together, the resulting motion is powerful and rapid.

"Multiple ultrathin wires provide a large surface area through which they can transfer heat, which means they can cool down very swiftly. As a result, the bundle of fibres can shorten and lengthen rapidly, making it possible for the gripper to grab or release an object very quickly," explains research assistant Susanne-Marie Kirsch. Kirsch and her colleague Felix Welsch are developing and optimizing the vacuum gripper technology as part of their doctoral research studies. "Currently, the gripper is able to securely hold objects weighing several kilograms. The gripper's lifting capacity is scalable, with correspondingly more wires being used in large grippers," explains Felix Welsch.

And because the material from which the wires are made has sensory

properties, the vacuum gripper is itself aware if the object is not being held securely. "The wires provide all the necessary information. The electrical resistance data correlates precisely with the extent of deformation of the wires. By interpreting the measurement data, the controller unit therefore knows the exact position of the wires at any one time," says Professor Seelecke. The gripper thus has an autonomous means of determining whether or not its [vacuum](#) is stable enough for the current task. It can also issue warnings in the event of a malfunction or material fatigue.

Provided by Saarland University

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