

Team develops autonomous robot to stave off spotted lanternflies

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TartanPest pairs computer vision with a robotic arm attached to an electric tractor to detect and destroy spotted lanternfly egg masses. Credit: Carnegie Mellon University

A team from Carnegie Mellon University's Robotics Institute (RI) has developed an autonomous robot to control the spread of spotted lanternflies, invasive insects known to destroy economically important crops.



TartanPest uses an all-electric tractor, a robotic arm and <u>computer vision</u> to traverse fields and forests while it detects and destroys spotted lanternfly egg masses. The egg masses—which contain 30–50 eggs and are often found on trees, rocks, outdoor furniture and rusty metal surfaces—are laid in the fall and hatch in the spring, birthing a new generation of the pests each year.

"Currently, spotted lanternflies are concentrated in the eastern portion of the nation, but they are predicted to spread to the whole country," said Carolyn Alex, an undergraduate researcher on the TartanPest team. "By investing in this issue now, we will be saving <u>higher costs</u> in the future."

The team created TartanPest by mounting a <u>robotic arm</u> to the base of an all-electric Amiga microtractor created by California-based robotics company Farm-ng. TartanPest uses a <u>deep learning model</u> refined on an augmented image data set created from 700 images of spotted lanternfly egg masses from iNaturalist to identify them and scrape them off surfaces.

Lanternflies feed on a wide range of plants and produce, including grapes, apples, hops, walnuts and many different hardwoods. In Pennsylvania alone, they have the potential to drain \$300 million from the economy annually. TartanPest could benefit small farmers and the broader food system by lowering the chemical pollution of crops, increasing efficiency on farms and saving labor costs for farmers.

Provided by Carnegie Mellon University

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