

## **Rapid laser solver for the phase retrieval problem**

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Detailed experimental digital ring degenerate cavity laser arrangement. SLM - spatial light modulator; PBS - polarizing beam splitter;  $\lambda/2@22.5^{\circ}$  - half-wave plate at 22.5° angular orientation;  $\lambda/2@45^{\circ}$  - half-wave plate at 45° angular orientation; compact support mask - intra-cavity aperture at the Fourier plane; OC–output coupler. Credit: Science Advances, doi: 10.1126/sciadv.aax4530



Physicists can explore tailored physical systems to rapidly solve challenging computational tasks by developing <u>spin simulators</u>, combinatorial optimization and focusing light through scattering media. In a new report on *Science Advances*, C. Tradonsky and a group of researchers in the Departments of Physics in Israel and India addressed the phase retrieval problem by reconstructing an object from its scattered intensity distribution. The experimental process addressed an existing problem in disciplines ranging from X-ray imaging to astrophysics that lack techniques to reconstruct an object of interest, where scientists typically use indirect iterative algorithms that are inherently slow.

In the new optical approach, Tradonsky et al conversely used a digital degenerate cavity laser (DDCL) mode to rapidly and efficiently reconstruct the object of interest. The experimental results suggested that the gain competition between the many lasing modes acted as a highly parallel computer to rapidly dissolve the phase retrieval problem. The approach applies to two-dimensional (2-D) objects with known compact support and complex-valued objects, to generalize imaging through scattering media, while accomplishing other challenging computational tasks.

To calculate the intensity distribution of light scattered far from an unknown object relatively easily, researchers can compute the source of the absolute value of an object's Fourier transform. The reconstruction of an object from its scattered intensity distribution is, however, illposed, since phase information can be lost and diverse phase distributions in the work can result in different reconstructions. Scientists must therefore obtain prior information about an object's shape, positivity, spatial symmetry or sparsity for more precise object reconstructions. Such examples are found in <u>astronomy</u>, <u>short-pulse</u> <u>characterization</u> studies, <u>X-ray diffraction</u>, <u>radar detection</u>, <u>speech</u> <u>recognition</u> and when <u>imaging across turbid media</u>. During the



reconstruction of objects with a finite extent (compact support), researchers offer a unique solution to the phase retrieval problem, as long as they model the same scattered intensity at a <u>sufficiently higher</u> <u>resolution</u>.



Basic DDCL arrangement for rapid phase retrieval. (A) Calculated scattered intensity distribution from the object (essentially the Fourier intensity distribution) is applied onto an SLM, which is incorporated into a ring degenerate cavity laser that can support up to 100,000 degenerate transverse modes. A mask shaped as the object boundaries (compact support) at the Fourier plane filters out extraneous modes that do not match the compact support. With this laser arrangement, the lasing process yields a self-consistent solution that satisfies both the scattered intensity distribution shown in (B) and the compact support constraint. (C) The reconstructed object intensity appears at the compact



support mask and is imaged onto the camera. a.u., arbitrary units. Credit: Science Advances, doi: 10.1126/sciadv.aax4530

Physicists had developed several algorithms to solve the phase retrieval problem in the last decade, including the <u>Gerchberg-Saxton (GS) error</u> reduction algorithm, <u>hybrid input-input algorithm</u> and <u>relaxed averaged</u> alternating reflections (RAAR). However, they are based on iterative projections that are relatively slow even on high performance computers. As an alternative, research teams can address computational challenges using specifically tailored <u>physical systems</u>. While such systems are not universal <u>Turing machines</u> (i.e., they cannot perform arbitrary calculations), they can potentially solve a <u>specific class of problems</u> efficiently. Solving difficult problems with such systems <u>can be</u> advantageous compared to the use of conventional computers.

Tradonsky et al experimentally demonstrated a new optical system to rapidly solve phase retrieval problems based on a <u>digital degenerate</u> <u>cavity laser</u> (DDCL). The device incorporated two constraints, including the Fourier magnitudes of scattered light from an object and the compact support. The nonlinear lasing process within the cavity resulted in a self-consistent solution that satisfied both constraints. The underlying physical mechanism in the DDCL was similar to that observed with <u>optical parametric oscillator</u> (OPO) spin stimulators.

Both OPO simulators and DDCLs have performed optimizations via <u>extremely fast operation</u> with ability to <u>avoid local minima</u> and possessed a <u>non-Gaussian wave packet</u>. The scientists facilitated the compact support aperture within the cavity to ensure different configurations of laser phases to result in different losses, to allow the configuration with minimal losses to win the mode competition and solve the phase problem. The DDCL system contained many attractive



and important features including high parallelism to provide millions of parallel experimental realizations, short round trip times approximating 20 nanoseconds, fast convergence times and an inherent selection mode that accounted minimal loss owing to mode competition. In theory, of all the time-evolving phase configurations, the one with the highest energy won the mode competition relative to the limited gain. As a result, larger the number of initial independent configurations in practice, higher the probability of the system to find a correct solution with a stable configuration and no losses.



LEFT: Experimental results for real-valued centrosymmetric objects. Column (A) Intensity distributions of the actual objects. Column (B) Detected intensity distribution of the reconstructed objects, using a circular aperture as compact support. Column (C) Fourier intensity distributions at the SLM. RIGHT: Experimental and quantitative results for fidelity as a function of object



complexity. Top: Representative intensity distributions of objects with 4, 16, and 30 spots. Column (A) Intensity (brightness) and phase (hue) distributions of the actual objects. Column (B) Detected intensity distribution of the reconstructed objects, using a circular aperture as compact support. Column (C) Calculated Fourier intensity distributions applied to control the SLM. Column (D) Detected corresponding Fourier intensity distributions after modifications by SLM properties. Bottom: Quantitative fidelity values of the Fourier intensity distributions (blue) and the reconstructed object intensity distributions (red) as a function of the number of spots in the object (4 to 30). Inset: Fidelity values of the Fourier intensity distributions for all the measurements. Credit: Science Advances, doi: 10.1126/sciadv.aax4530.

In the experimental setup, Tradonsky et al included a ring degenerate cavity laser with an inherent gain medium, two 4f telescopes and an amplitude spatial light modulator (SLM). The system also included an intracavity aperture, 3-D reflectivity mirrors and an output coupler. The team used the left 4f telescopes to image the center of the gain medium onto the SLM and <u>controlled the transmission at each pixel</u>, independently. They combined the intracavity aperture with the SLM to control and form the output lasing intensity distribution. When the scientists placed an intracavity aperture (compact support mask) at the Fourier plane between the two lenses, each phase distribution demonstrated a different level of loss. Consequently, the phase distribution with minimal loss was the most probable lasing mode in the study. The team considered two figures of merit to quantify the quality of the system including solution fidelity and computation time. The research team obtained representative results for centrosymmetric objects with very good agreement between intensity distributions of the original (actual object) and reconstructed forms.





Experimental results demonstrating the qualitative effect of tightness and asymmetry of compact supports. Column (A) Intensity distribution of the actual objects. Column (B) Detected intensity distribution of the reconstructed objects, using a circular aperture as compact support. Column (C) Detected intensity distribution of the reconstructed objects, using a square aperture as tight compact support (top row) and a circular aperture with a wedge as asymmetric compact support (bottom row). Column (D) Fourier intensity distributions at the SLM. Credit: Science Advances, doi: 10.1126/sciadv.aax4530

Tradonsky et al measured the effect of object complexity on reconstruction fidelity and formed representative intensity distributions for objects with four, 16, and 30 spots. The results showed that higher complexity objects (those with more spots) showed higher-complexity Fourier intensity distribution, with intricate detail that could not be resolved using the present system. They also noted the input and reconstruction fidelities to decrease with increasing object complexity, which they credited to the fluctuating technical noise of the laser pump.



They conducted qualitative experiments to assess the effect of tightness and symmetry during object reconstruction. The results showed that a tight compact support significantly improved the quality of the reconstructed object.

The team then investigated the quantitative effects of the radius of the compact support aperture on the quality and fidelity of reconstruction. For bigger objects the representative intensity underwent rapid decay during reconstruction fidelity since the laser was unable to support the object shape. With objects smaller than the compact support aperture, Tradonsky et al observed slower decay in fidelity. In total, they observed reduced reconstruction fidelity when the camera averaged across multiple realizations of an <u>object</u> within the system.



Experimental quantitative results for reconstruction fidelity as a function of the compact support radius of the aperture normalized by the object size. Insets: Typical reconstructed object intensity distributions. (A) Compact support radius



is 87% of the object radius. (B) Object radius is equal to compact support radius. (C) Compact support radius is 152% of the object radius. Credit: Science Advances, doi: 10.1126/sciadv.aax4530.

Generally, the resolution of the reconstructed objects was relatively low due to phase aberrations in the laser cavity. The team proposed to optimize the system and reduce aberrations for improved resolution. The scientists also analyzed the time taken to offer a reconstruction solution using the system and found the durations dictated by the SLM (spatial light modulator) and the camera readout to approximate 20 ms. The actual computation time of lasing only lasted less than 100 nanoseconds. When Tradonsky et al optimized the experimental setup using a Qswitched linear degenerate cavity laser arrangement with pockel cells, they reduced the total computation time of the system to approximately 100 nanoseconds. Comparatively, the reconstruction time with the RAAR algorithm lasted one second.

In this way. C. Tradonsky and colleagues presented an optical system for rapid phase retrieval using a new DDCL (digital degenerate cavity laser). The computation time amounted to 100 nanoseconds; orders of magnitudes faster than conventional, algorithm based computational systems. Based on the results, several modifications to the DDCL system can potentially improve its performance, including increased length of the laser cavity to increase the number of independent parallel investigations. The research team will further explore the system to solve a variety of problems and resolve imaging quality after propagation through scattering media.

**More information:** C. Tradonsky et al. Rapid laser solver for the phase retrieval problem, *Science Advances* (2019). <u>DOI:</u> <u>10.1126/sciadv.aax4530</u>



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