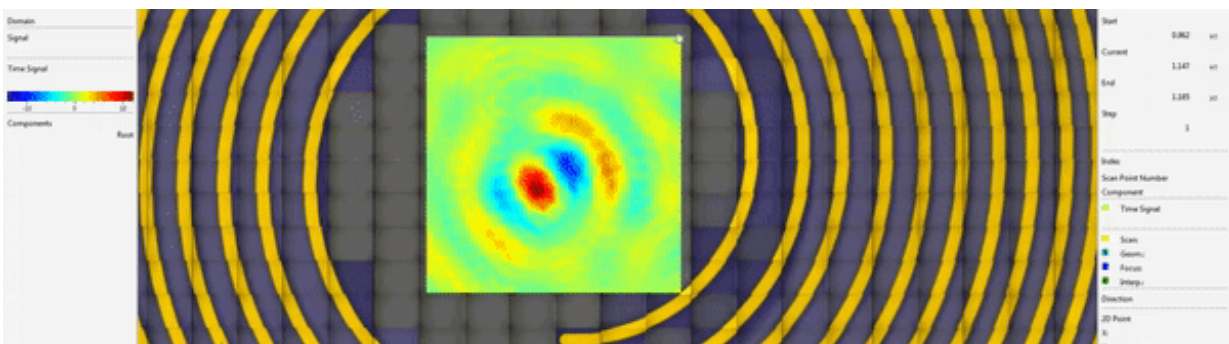


Folding an acoustic vortex on a flat holographic transducer to form miniaturized selective acoustic tweezers

April 18 2019, by Thamarasee Jeewandara



Movie showing an animation of the vortex measured experimentally with a laser interferometer. Colors correspond to the amplitude of the normal displacement at the surface of the coverslip. Credit: Science Advances, doi: 10.1126/sciadv.aav1967

Acoustic tweezers are based on focused [acoustic vortices](#) and hold promise to precisely manipulate microorganisms and cells from the millimeter scale down to the submicron scale, without contact, and with unprecedented selectivity and trapping force. The widespread use of the technique is hindered at present by limitations to the existing systems stemming from performance, miniaturization and the inability to assimilate in compartments. In a recent study, Michael Baudoin and colleagues at the Sorbonne University and the French National Center

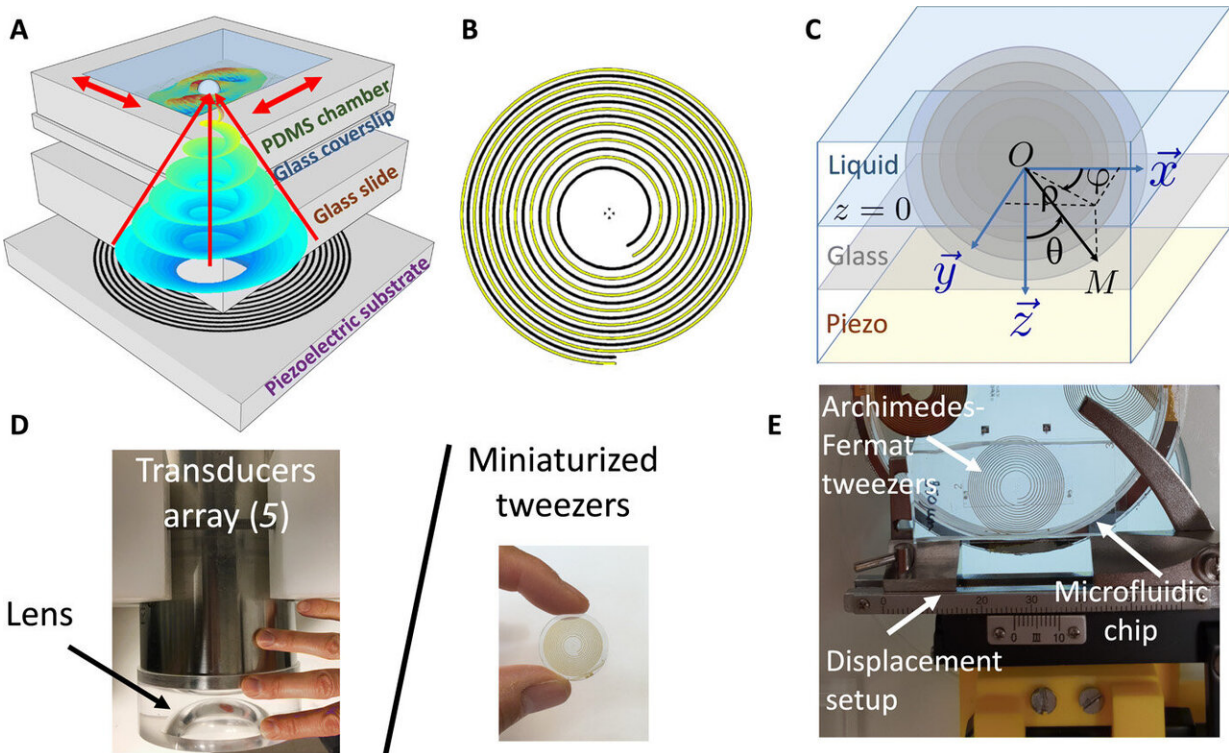
for Scientific Research (CNRS), improved the potential of focused acoustic vortices by developing the first flat, compact and paired single electrode focalized or focused '[acoustical tweezer](#)'.

The invention relied on spiraling [transducers](#) that were engineered by folding a spherical acoustic vortex on a flat [piezoelectric](#) substrate. Baudoin et al. demonstrated the ability of these [acoustic tweezers](#) to grab and displace micrometric objects within a microfluidic environment with unique selectivity. The system is simple and scalable to higher frequencies; opening tremendous perspectives in microbiology, microrobotics and microscopy. The results are now published in *Science Advances*.

The first reported observations of partial levitation in acoustic wave fields date back to the work of [Boyle and Lehmann](#) in 1925. Precise and contactless manipulation of physical and biological objects at the micrometer scale down to the nanometer scale has promising applications in the modern, diverse fields of microrobotics, tissue engineering and micro/nanomedicine. Acoustic tweezers are a prominent technology to accomplish the task as they are [noninvasive](#), biocompatible and label-free. They are also able to trap forces that are [several orders of magnitude larger](#) than their optical counterparts, at the same actuation power. However, only recently have scientists simultaneously developed [advanced wave synthesis systems](#), microfluidic setups and the theory of acoustic radiation pressure, to allow the potential of [acoustophoresis](#) (motion with sound) to be harnessed.

Until recently a majority of acoustical tweezers relied on a single, or set of orthogonal standing waves to [create a network of nodes and antinodes](#) to trap particles. While these systems were highly efficient for the collective manipulation of particles and cells, the system prevented specific selectivity. While limited localization of the acoustic energy could be achieved using the [original sub-time-of-flight technique](#), only

the strong focus of wave fields could allow specific selectivity at the level of the single particle.



Principle of the Archimedes-Fermat acoustical tweezers: (A) Scheme illustrating the composition of the Archimedes-Fermat acoustical tweezers: A focalized acoustical vortex is synthesized by spiraling metallic electrodes deposited at the surface of a piezoelectric substrate. The vortex propagates and focalizes inside a glass slide (sealed with the piezoelectric substrate) and a mobile glass coverslip before reaching the liquid contained in a polydimethylsiloxane (PDMS) chamber, wherein the particle is trapped. The mobility of the microfluidic chip (glass coverslip and sealed PDMS chamber) is enabled by a liquid couplant and a manual precision displacement setup represented in (E). (B) Spiraling pattern of the electrodes obtained from approximated equations derived in the study. (C) Scheme introducing the spherical (r, θ, φ) and cylindrical coordinates (ρ, φ, z) used for the demonstration of equation derived in the study (D) Comparison of the compactness of the transducer array developed in a previous study (left) to the Archimedes-Fermat acoustical tweezers presented in this paper (right). This

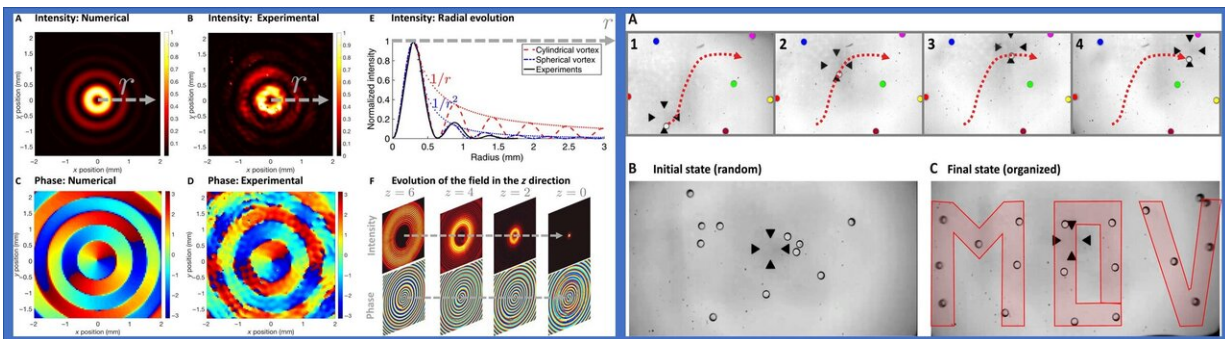
figure also shows the transparency of the Archimedes-Fermat acoustical tweezers (particles are trapped on the central axis of the transducer). Photo credit: Jean-Louis Thomas, CNRS (left) and Michael Baudoin, Université de Lille (right). (E) Image showing the integration of the Archimedes-Fermat acoustical tweezers into a Leica Z16 microscope. Four tweezers have been patterned on a 3-inch LiNbO₃ wafer. Photo credit: Jean-Claude Gerbedoen, SATT Nord. Credit: Science Advances, doi: 10.1126/sciadv.aav1967

Focused acoustic waves are therefore natural candidates to achieve this level of localization but many particles of interest (cells and rigid fragments) can migrate to the standing wave nodes to be expelled from the wave focus, thwarting [research efforts](#) on engineering a selective acoustical tweezer. While a [wealth of systems](#) were previously proposed to synthesize acoustic vortices, the ability to [retain a 3-D trap and pick a specific particle](#) independently of its neighbors was only recently demonstrated using a [strong focused acoustic vortex](#). Acoustic vortices thus synthesized rely on [transducer arrays](#) or passive systems that are cumbersome and [incompatible within microsystems](#) (microfluidics and microchips).

In the present work, Baudoin et al. therefore harnessed the potential of selective acoustic tweezers by folding the phase of a focused acoustic vortex on a flat surface. To accomplish this, they followed the principle of [Fresnel lenses](#) and synthesized acoustic vortices with single spiraling [interdigitated electrodes](#) deposited at the surface of a piezoelectric substrate. They materialized two [equiphase lines](#) using the electrodes to represent the folded phase on two discrete levels. The shape of the electrode was similar to an [Archimedes-Fermat spiral](#), where its radial contraction allowed wave focusing without the requirement of a curved transducer or lens, as a major advantage compared to existing systems. Baudoin et al. were also able to overcome all limitations of the previously demonstrated cylindrical vortex-based tweezers to presently

demonstrate higher selectivity. In the study, the scientists used the development to:

1. Measure the acoustic field with a laser interferometer and quantify the fast-radial decrease of secondary rings (rings of weaker amplitude that can impede selectivity) in the system, and
2. Selectively trap and move one particle independently of its neighbors within a standard microfluidic environment, demonstrating its practicality.



LEFT: Field synthesized by an Archimedes-Fermat acoustical tweezers: Theory versus experiments. (A) Numerical predictions with the angular spectrum method and (B) experimental measurements with a UHF-120 Polytec laser interferometer of the normalized intensity of the vibration at the surface of the glass coverslip (focal plane, $z = 0$). The maximum amplitude measured experimentally (on the first ring) is 10 nm. (C) Numerical predictions with the angular spectrum method and (D) experimental measurements with the laser interferometer of the phase of the acoustic wave at the surface of the glass coverslip. (E) Radial evolution of the normalized intensity of the acoustic wave from the center of the vortex to the side, as a function of the lateral radius r in millimeters. Black solid line: Average over all angles φ of the intensity measured experimentally. Red dashed line: Evolution expected for a cylindrical vortex (cylindrical Bessel function). Blue dashed-dotted line: Evolution expected for a spherical vortex (spherical Bessel function). Red dotted line: Asymptotic evolution in $1/r$. Blue dotted line: Asymptotic evolution in $1/r^2$. (F) Evolution of

the field intensity (top) and phase (bottom) in the z direction. The direction of the arrow indicates the wave propagation direction. Left to right: Distances $z = 6, 4, 2,$ and 0 mm, respectively ($z = 0$ corresponds to the focal plane). Top: Localization of the acoustic energy and formation of a localized trap. Bottom: Transition from a Hankel to a Bessel spherical beam. RIGHT: Microparticles' selective displacement in a standard microscopy environment. (A) Selective manipulation of a polystyrene particle having a radius of $75 \pm 2 \mu\text{m}$ with the 4.4-MHz selective acoustical tweezers based on Archimedes-Fermat spirals. This figure shows that only the particle trapped at the center of the vortex (located just above the lowest arrow) is moved, while the other particles remain still. The particles at rest have been colored to improve the readability of the figure. (B and C) Patterning of 18 polystyrene particles with a radius of $75 \pm 2 \mu\text{m}$ into prescribed position to form the letters M, O, and V (moving object with vortices). (B) Randomly dispersed particles (initial state). (C) Organized particles (final state). Credit: Science Advances, doi: 10.1126/sciadv.aav1967

The scientists designed the experimental system to synthesize focal vortices at a frequency of 4.4 MHz, with spiraling metallic electrodes that were deposited at the surface of a Y-36 [niobate lithium](#) (LiNbO_3) piezoelectric substrate. To drive the vibration of these spiraling electrodes the scientists used a waveform generator and an amplifier for beam convergence during the experiment within an aqueous microfluidic setup consisting of a glass coverslip and polydimethylsiloxane (PDMS) chamber. They ensured better transmission of acoustic energy from the glass to the liquid in the experimental setup and used a Polytec laser vibrometer to measure the resulting acoustic field at the surface of the glass coverslip.

In the experimental setup, Baudoin et al. used metallic electrodes deposited on the surface of the piezoelectric substrate to synthesize converged [Hankel beams](#) of finite aperture. They excited each electrode to provoke localized vibrations on the piezoelectric substrate and

produce a bulk acoustic vortex inside a glass slide. In this holographic method, they combined several concepts in the field of microelectronics, including the underlying physical principles of Fresnel lenses in optics, the specificity of [Bessel beam topology](#) and the principles of wave synthesis with [interdigital transducers](#) (IDTs).



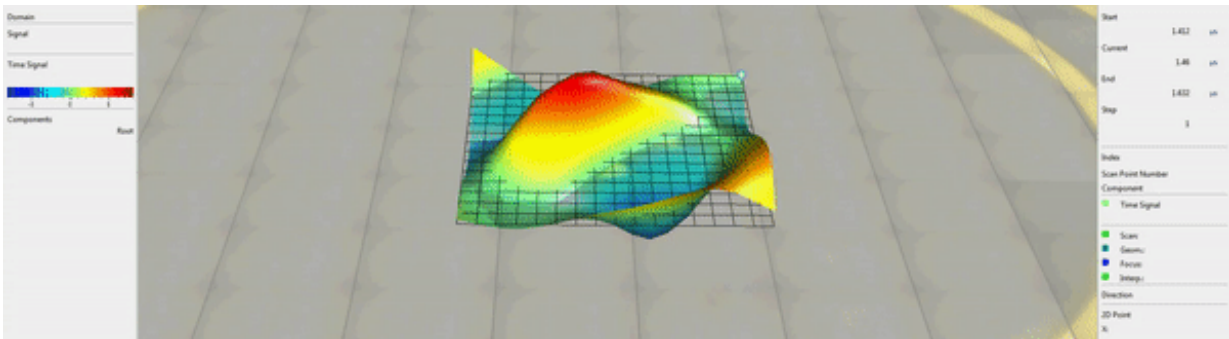
Movie showing the selective manipulation of polystyrene particle having a radius of $75 \pm 2 \mu\text{m}$ with the 4.4-MHz selective acoustical tweezers based on Archimedes-Fermat spirals. Credit: Science Advances, doi: 10.1126/sciadv.aav1967

Spherical acoustic Bessel beams are spherical vortices that form excellent candidates to create a localized acoustic trap. Mechanistically, these acoustic fields can focus the acoustic energy in 3-D to create a shadow zone in the [vortex center surrounded by a bright shell](#) to trap particles. Much like a plane standing wave is a combination of two counterpropagating traveling waves, a spherical Bessel beam results from the interference between a converging and diverging spherical [Hankel beam](#).

As a result, a Bessel beam can be experimentally produced by a single Hankel converging beam that interferes with its diverging counterpart generated at the focus, i.e. within the vortex central singularity. Due to the piezoelectric effect, the scientists were able to couple the mechanical vibrations of the bulk acoustic waves to the electric potential and model the electrodes as perfect wires ([isopotential lines](#)). Using the two electrodes, Baudoin et al. discretized the folded phase on two levels to form the acoustic tweezers.

The scientists compared the acoustic field measured experimentally with the numerical predictions obtained from the [angular spectrum method](#) to show excellent agreement between both, for the intensity and phase of the wave field. They compared the experimentally measured and averaged radial evolution of the ring's intensity to (1) the radial evolution of a cylindrical vortex (red) and (2) the radial evolution of a spherical vortex (blue). The results showed that since the radiation pressure was

proportional to the beam intensity, the selectivity was greatly enhanced by axial focusing of the beam compared to cylindrical vortices. In this way, the scientists showed 3-D focalization of the energy as a major advantage to selectively manipulate the particles.



Movie showing the localization of the vortex core. Credit: Science Advances, doi: 10.1126/sciadv.aav1967

To demonstrate the acoustical tweezer's ability to pick a particle and move independently of its neighbors, Baudoin et al. dispersed monodisperse polystyrene particles with a radius of $75 \pm 2 \mu\text{m}$ inside the microfluidic chamber with a height of $300 \mu\text{m}$. The tweezers picked a specific particle made of polystyrene, where the weak density and compressibility of particles contrasted with the surrounding liquid. According to a [previous report](#) the trapping force exerted on solid particles by a first-order Bessel beam strongly relied on the contrasting density and/or compressibility; weaker the contrast – weaker the trapping force. Only the particles trapped at the center of the vortex moved, while the others remained still. Using the technique, the scientists demonstrated the ability of the tweezer to precisely position a set of 18 polystyrene particles with a radius of $75 \pm 2 \mu\text{m}$ starting from random distribution in to a prescribed pattern to spell 'MOV' (Moving

Objects with Vortices).

In total, Baudoin et al. lifted existing restrictions of acoustic tweezers that had thus far forced a trade-off between selectivity and miniaturization or integration, preventing their applications in microfluidics and microbiology. They overcame the limitations through (1) acoustic trapping with focused vortices, (2) holographic wave synthesis with IDTs and (3) integration of the principles of Fresnel lenses within a single, compact and transparent miniaturization device.

Using the microsystem, the scientists demonstrated contactless manipulation of [particles](#) within a standard microscopy environment with state-of-the-art selectivity. Due to the simplicity of the technology and scalability to higher frequencies, the work can pave the way towards individual manipulation and in situ assembly of physical and biological micro-objects.

The rigorous demonstration of real 3-D trapping with a progressive wave will require the elimination of any standing waves that may appear from wave reflections in a confined setup. The practical demonstrations of 3-D trapping capacity of the Archimedes-Fermat tweezers will present an interesting perspective in microrobotics, tissue engineering and nanomedicine.

More information: Michael Baudoin et al. Folding a focalized acoustical vortex on a flat holographic transducer: Miniaturized selective acoustical tweezers, *Science Advances* (2019). [DOI: 10.1126/sciadv.aav1967](https://doi.org/10.1126/sciadv.aav1967)

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