

Five things to consider before speed limiters are added to cars

March 29 2019, by John Mcdermid



Credit: Unsplash/CC0 Public Domain

The recent announcement that EU rules for <u>fitting speed limiters to new</u> <u>cars</u> from 2022 will be adopted by the UK was welcomed by many, including the European Transport Safety Council, as a move that will



save lives. However, not everyone is convinced by this "guardian angel" technology.

The AA pointed out that there are times, when overtaking for example, when temporarily exceeding the <u>speed</u> limit may be safer. Others have said that proposed "<u>black boxes</u>" that would record a vehicle's speed, among other things, amount <u>to big brother surveillance</u>. So is this surveillance and intrusion justified given the potential benefits?

Speed assistance technology uses a Global Positioning System (GPS) to establish a car's location and then sends it a message about the road's speed limit. Cars can also be fitted with a camera to identify speed limit signs by the road. The car – rather than the driver – would use these two inputs to keep below the speed limit. The technology the EU proposes would allow <u>drivers</u> discretion, however, so a driver would have the option to override the reduction in speed by pushing the accelerator.

This technology, which is already available in some cars, can be seen as a step towards Autonomous Vehicles (AVs) which will need to respect <u>speed limits</u>. But there are still a number of more detailed issues we need to address to resolve the question of whether the pros outweigh the cons.

Theory vs reality

First, how would such technology influence driver behaviour and what impact would this have on overall safety and driving skills? <u>A study of</u> <u>Volvo employees</u> showed that drivers of AVs build trust in the autonomy of a car. In experiments, the drivers were told that they had responsibility for emergency braking, but when faced with an emergency situation only a third applied brakes promptly, a third applied them late, and a third not at all.

Before introducing speed assistance, then, we need to understand how



drivers will respond to such technology: will they always drive at the speed limit, relying on the car's autonomy – even where lower speeds would be more appropriate, for example in more difficult road conditions such as ice or snow?

Second, how do we show the safety of the system before it is launched, or even used in trials? Technologically, this does not seem too challenging. But the critical thing will be to identify scenarios that might confuse a system and which could lead to inappropriate decisions. For example, what would happen in a contraflow on a motorway, where one lane goes in the opposite direction to the rest of the traffic? (Hopefully, the system wouldn't think it should reverse.)



Credit: AI-generated image (disclaimer)



Third is the issue of safe interaction between speed assistance and other systems – often referred to as a system of systems (SoS) problem. This is true for a single car; how will the speed limiter interact with cruise control, autonomous emergency braking, and so on? It is also true between vehicles – what is a sensible deceleration profile on moving from, say, a 60mph to a 30mph limit? Should that profile be different if the car is being followed very closely by a heavy goods vehicle? If so, how will the car sense this? These problems are being addressed by developers of AVs, for example by having sensors to detect the proximity of vehicles behind, as well as in front, of the car.

Then there is the issue of ethics, or moral responsibility. A possible unintended consequence of introducing such technology is the creation of what are called <u>"responsibility gaps"</u> – characterised simply as situations where nobody has enough control over a system's actions to assume responsibility for them.

For example, if the speed limiter is slowing the car down (braking) as it approaches a lower speed limit, and the driver presses the accelerator to get past an obstacle quickly, will the driver or system "win"? And what if the driver was right, but the system hasn't left a big enough margin for error for the driver to make a correction? This might be seen as a responsibility gap.

Fifth, the Law Commission, the organisation that reviews laws in England and Wales, is running a <u>study into the law related to AVs</u>. The study questions whether or not AVs should be allowed to break the speed limit. My view is that all the manoeuvres the car plans to undertake should be defined to stay within limits, but an AV should be allowed to exceed the limit, where this minimises the risk, such as completing an overtaking manoeuvre where road conditions have changed unpredictably since starting to overtake. Drivers will have discretion over this – but we would still need to know how drivers would respond to



the technology.

Black boxes for cars

While some see the proposed "black boxes" as a big brother device, they are likely to facilitate better accident and incident investigation and potentially be very beneficial to overall road safety.

Analysis of data from flight recorders in the aerospace industry has been a major factor in improving flight safety. But a key point here is defining what is recorded. Consider the SoS problem – what do we need to know about other systems in the car and would we need data from the black boxes in other vehicles to get a full understanding of an accident? Nonetheless, black boxes in cars could be a much greater contribution to road safety in the long run than speed limiters, especially as we move towards AVs.

It seems likely that this technology can be net beneficial; a guardian angel that is also a fairly benevolent big brother. But studies will need to confirm this and some of the other issues that speed assistance technology raises. As it currently stands, <u>the proposals are</u> "driving as imagined" not "driving as done". We need to be as sure as possible that these proposals are beneficial in the real world, with real drivers on real roads, not just in theory.

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