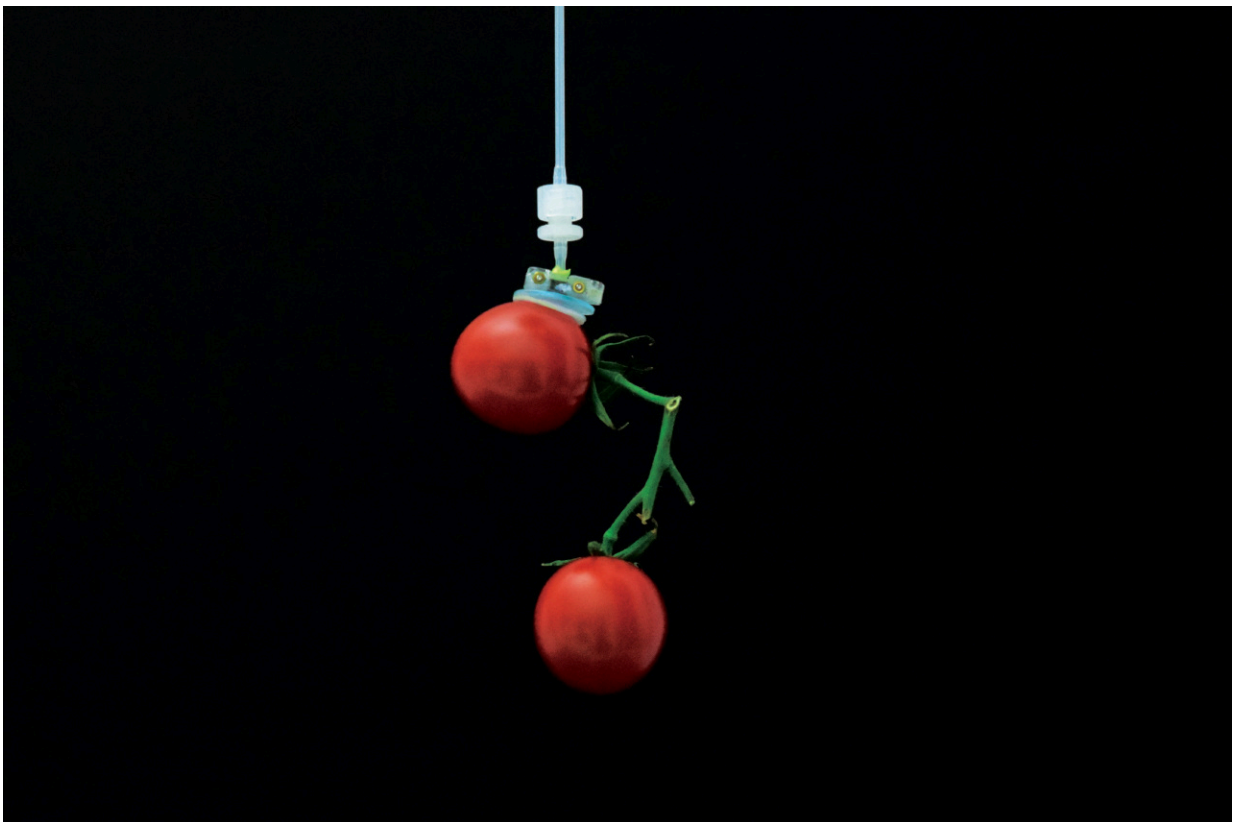


Inspired by geckos, researchers engineer soft gripping system that outperforms current adhesion methods

May 18 2017, by Lisa Kulick



The soft adhesion-based gripping system holds a pair of cherry tomatoes weighing 41 grams. Credit: Carnegie Mellon University

Researchers at Carnegie Mellon University and Max Planck Institute for

Intelligent Systems [have developed a soft gripping system](#) that uses differential air pressure and a gecko-inspired adhesive for exceptional bonding to three-dimensional objects. The findings were published in *Proceedings of the National Academy of Sciences* this week.

A soft gripping system capable of strong and reversible adhesion to non-flat surfaces is particularly critical for applications in transfer printing, robotics, and precision manufacturing. In these areas, adhesion-controlled grasping of complex three-dimensional surfaces is very challenging because the adhesive must be soft enough to enable intimate contact under light pressure but stiff enough to support high load and fracture strength.

"Until now, there has been a fundamental trade-off between soft, mechanically compliant interfaces and high adhesion strength," said Metin Sitti, a director in Max Planck Institute for Intelligent Systems. "With this soft gripping system, we've demonstrated that you can have both."

Sitti, also an adjunct professor of [mechanical engineering](#) at Carnegie Mellon University, has long focused his research on the unique features of the gecko lizard.

The gripping system contains a soft adhesive membrane with microscopic pillars that are inspired by the sticky foot hairs on a gecko's foot. The membrane is supported by a deformable gripper body that controls the gripping strength of the adhesive through changes in internal air pressure. It exhibits enhanced and robust adhesion on various sizes of curved and deformable surfaces, outperforming other [adhesion](#) methods.



Geckos can climb walls because they have microscopic, hairlike structures on their feet. Credit: Pixabay

Another area of application for this soft gripping system is in personal robotics.

"One day, we might have robots that act as assistants and care-givers—for example, a robot that can help unload a dishwasher or manage medication. The ability for the robot to manipulate a broad range of objects is crucial," said Carmel Majidi, an associate professor of mechanical engineering at Carnegie Mellon.

Majidi and Sitti acknowledge Sukho Song and Dirk-Michael Drotlef in performing this multidisciplinary research and the Max Planck Society

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More information: "Controllable load sharing for soft adhesive interfaces on three-dimensional surfaces," *Proceedings of the National Academy of Sciences*, [DOI: 10.1073/pnas.1620344114](https://doi.org/10.1073/pnas.1620344114)

Provided by Carnegie Mellon University Mechanical Engineering

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