

# Perfect skin: More touchy-feely robots

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Credit: AI-generated image ([disclaimer](#))

Robots could become a lot more 'sensitive' thanks to new artificial skins and sensor technologies developed by European scientists. Leading to better robotic platforms that could one day be used in industry, hospitals and even at home.

The new capabilities, and a production system for building touch-sensitivity into different robots, will improve the way robots work in

unconstrained settings, as well as their ability to communicate and cooperate with each other and with humans.

The EU-funded project 'Skin-based technologies and capabilities for safe, autonomous and interactive robots' (ROBOSKIN) developed new [sensor technologies](#) and management systems which give robots an artificial [sense of touch](#) - until now an elusive quality in robotics.

According to the partners behind the research from Italy, Switzerland and the UK, it was important to create [cognitive mechanisms](#) that use [tactile feedback](#) (the sense of 'touch' or 'feel') and behaviour to make sure human-[robot](#) interaction is safe and effective for the envisaged future applications.

The [artificial skin](#) is modelled largely on real skin, which has a tiny network of nerves that sense or feel changes like hot/cold or rough/smooth. In this case, the [electronic sensors](#) collect this so-called 'tactile data' and process it using application software which has been front-loaded to include some basic robot behaviours which can be added to over time.

'Here, we opted for programming through demonstration and robot-assisted play so the robots learn as they go along by feeling, doing and interacting,' explains project coordinator Professor Giorgio Cannata of Genoa University, Italy.

'We had to generate a degree of awareness in the robots to help them react to tactile events and physical contact with the outside world,' he adds.

## **Kaspar the friendly robot**

But robot cognition is extremely complex, so ROBOSKIN started with

modest ambitions in [lab tests](#) by classifying types or degrees of touch. They created a geometric mapping using continuous contact between the test robot and the environment to build a 'body representation' - parameters by which data can be assimilated by the robot into behaviour.

Outside the lab, on the other hand, ROBOSKIN sensor patches were applied to common touch points (feet, cheeks, arms) located on the University of Hertfordshire's [KASPAR](#) robot, a humanoid robot designed to help autistic children communicate better.

'With our sensors, the robot could sense or detect contact and the data collected formed an important part of the contact classification we did - the distinction between, for example, wanted and unwanted touch,' explains Prof. Cannata.

ROBOSKIN scientists explored various technologies, from the more basic capacitive sensors in today's sensing technologies, to higher-performing transducers found in piezoelectric materials, and flexible organic semiconductors.

'We'll see more and more piezoelectric materials - which can act like sensors because they react to changes brought on by contact with an outside force - in the near future,' predicts Prof. Cannata. But sensors using organic semiconductors will be the future game-changer, he suggests, as you will be able to print the chips on different organic materials like fake skin or bendable materials, and they will eventually be much cheaper to make, once scaled up.

## **Promoting the prototypes**

The ROBOSKIN funded project ended last summer but the researchers are actively promoting the findings through scientific channels, including papers in 'IEEE Xplore' and 'Science Direct', as well as calls for interest

in sharing their prototypes with non-commercial research projects.

Tactile sensors are not new by any means, stresses Prof. Cannata, but ROBOSKIN has succeeded in developing a production system for building tactile sensing into different robots. These unique methods solve the decades-old problem of adding more sensory perception to robots.

'We are still at the pre-commercial demonstrator stage, but the latest version of our tactile sensors clearly have wider potential in industry as factories seek safe, cost-efficient ways of using robots in closer contact with human workers,' explains the coordinator.

Patents have been filed for parts of the team's work, but they stress that prototypes remain available for scientific research work. ROBOSKIN technology has already been integrated into iCub, the Italian Institute of Technology's open robotics platform.

'The key was to ensure that our basic technologies would be compatible across different robotic platforms that may evolve in this fast-moving field,' notes Prof. Cannata. 'And this is what we have achieved.'

The ROBOSKIN project received EUR 3.5 million (of total EUR 4.7 million project budget) in research funding under the EU's Seventh Framework Programme (FP7).

**More information:** ['Skin-based technologies and capabilities for safe, autonomous and interactive robots'](#) website

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