

It's all in the way we move

March 13 2013

When, how and why modern humans first stood up and walked on two legs is considered to be one of the greatest missing links in our evolutionary history. Scientists have gone to the far ends of the earth – and the wonderful creatures in it - to look for answers to why we walk the way we walk.

In the latest such search, researchers from the University of the Witwatersrand in Johannesburg (South Africa) have taken a closer look at bipedal [kangaroos](#) and wallabies and how they move compared to their cousin-marsupials, such as the quadrupedal Tasmanian wolf.

In an article published online in the scientific journal *PLoS ONE* on Tuesday, 12 March 2013, the researchers examine connections between bone form and locomotor behaviour in bipedal and quadrupedal marsupials. [Read the article here](#)

The study was led by Dr Kristian Carlson, Senior Researcher at the Institute for [Human Evolution](#) (IHE) at Wits University. Contributing authors include: Dr Tea Jashashvili, Postdoctoral Fellow at the IHE at Wits University; Kimberley Houghton, MSc candidate at the IHE at Wits University; Dr Michael Westaway from the Queensland Museum (Australia); and Dr Biren Patel from the University of Southern California (US).

Their article is entitled "Joint loads in marsupial ankles reflect habitual bipedalism versus quadrupedalism." The research demonstrates that bipedal marsupials, such as kangaroos and [wallabies](#), experience greater

forces through their hind limb joints (e.g., ankles) when walking, compared to other marsupials that walk on four legs.

The study has several important implications in the area of research known as functional morphology.

Characterising forces that joints experience during movement is imperative to understanding how the joints of animals function and facilitate such movements. Documenting these forces, however, is extremely difficult for practical reasons.

Using physical instruments to measure joint forces is impossible without altering the natural movements of animals. By combining computed tomography (CT) and image analyses, the team of researchers was able to estimate joint forces in a non-invasive, accurate manner.

As the group predicted at the outset of the study, marsupials supporting their body with only two hind limbs during movement sustain higher estimated forces in their joints compared to marsupials that support their body with all four limbs during movement. This finding offers insight into the structural uniqueness of hind limb joints (e.g., ankles) of bipedal marsupials.

Members of the team are currently expanding the published study into the next phase of a larger project by documenting the same phenomenon in primates in order to investigate whether bipedal humans differ from related quadrupedal primates in parallel (or different) ways as bipedal marsupials differ from related quadrupedal marsupials.

By comparing analogous systems in primates and [marsupials](#), team members will garner potentially new insights into the mechanics of human bipedalism. Such insights will advance current understanding of the morphological adaptations expressed by our distant hominin

ancestors (e.g., australopithecines).

These insights will prove particularly timely considering the emerging trend in recognizing substantial variation in the form of bipedalism expressed by our hominin ancestor.

Provided by Wits University

Citation: It's all in the way we move (2013, March 13) retrieved 24 April 2024 from <https://phys.org/news/2013-03-it-all-in-the-way.html>

This document is subject to copyright. Apart from any fair dealing for the purpose of private study or research, no part may be reproduced without the written permission. The content is provided for information purposes only.