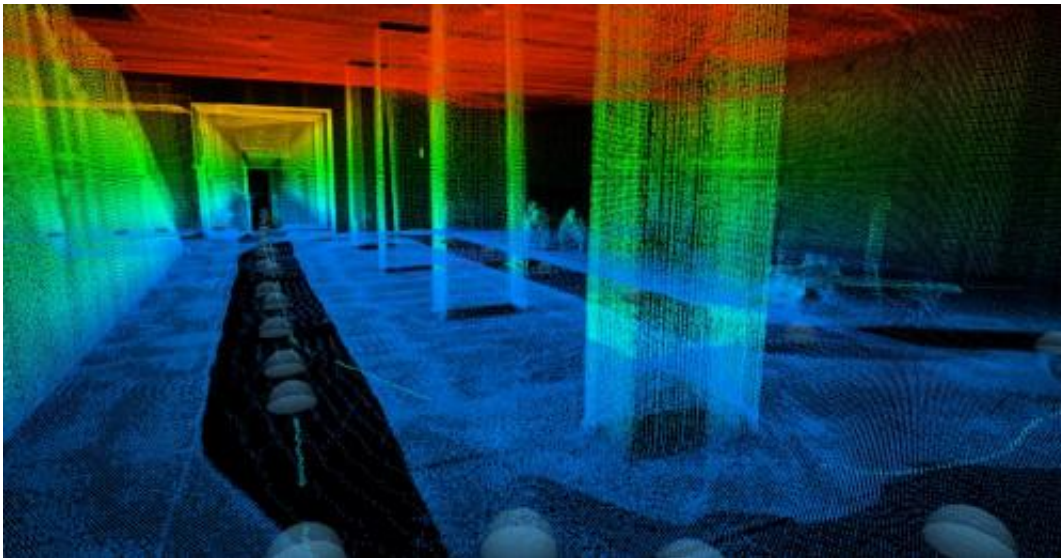


Improving positioning indoors with imaging data

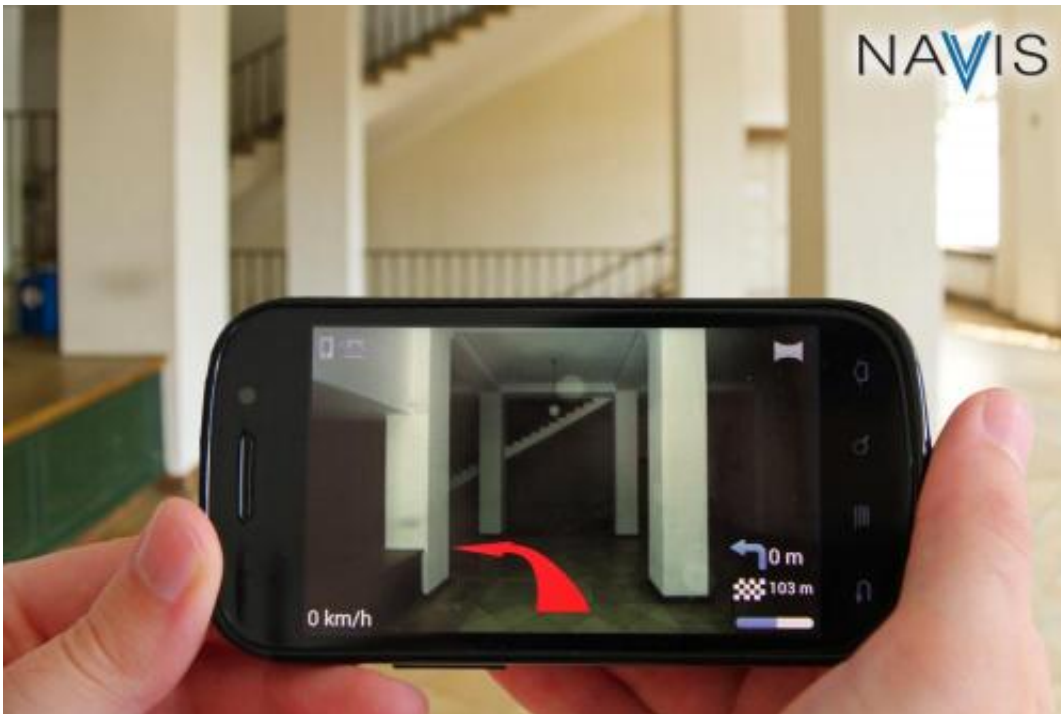
September 17 2012



For the mapping NAVVIS uses both vertical and horizontal laser scans. The environment is displayed as a three-dimensional point cloud. Credit: G. Schroth/TUM

Whether you're walking, biking or driving, navigation systems can help you get from A to B - as long as you have a GPS signal. To find our way around large and complex buildings like hospitals or airports, we often need to rely on vague signs. Researchers at Technische Universitaet Muenchen have come up with a new technology. The NAVVIS system uses visual information and realistic 3D images to point users in the right direction.

The NAVVIS positioning system is primarily based on [visual information](#). The TUM researchers had to develop a special [location recognition system](#) for this project. They started by taking photos of a building, simultaneously mapping prominent features like stairs and signs. A smartphone app then lets users view the map images to find their current location. All they have to do is take a photo of their surroundings. The program then compares the photo with the images stored in its database and works out the user's exact position (down to the nearest meter) and the direction in which they are facing. The app uses arrows to point the way in a 3D view.

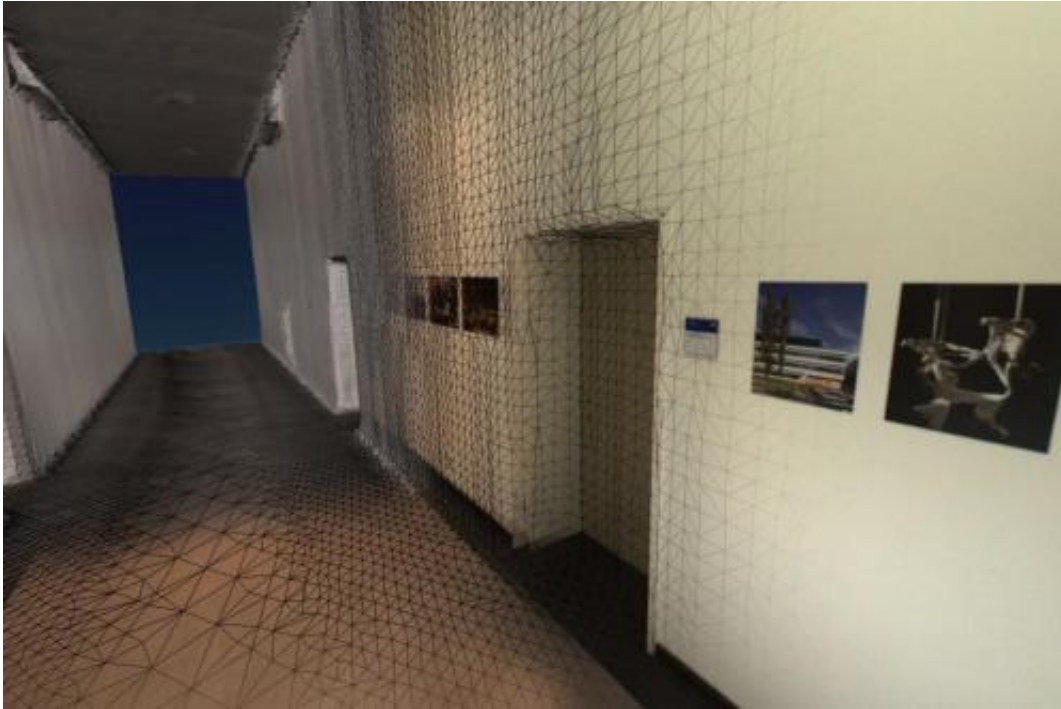


NAVVIS uses realistic 3D images to point users in the right direction. Credit: G. Schroth/TUM

NAVVIS is currently being tested at TUM: "With multiple floors and winding corridors, the main campus is something of a maze after several

decades of expansion. This makes it an ideal testing ground for NAVVIS," declares Georg Schroth, who is heading up the project at TUM's Institute for Media Technology. NAVVIS has other potential uses besides navigation, as his colleague Robert Huitl explains: "The software can also be used for augmented reality applications if you add on special programs. So for instance, visitors to the [Louvre](#) would not only be able to locate the Mona Lisa, but also view information about the painting or find directions to other works by da Vinci." Another possibility would be virtual tours on a PC or smartphone.

NAVVIS is suitable for all places beyond the reach of [satellite navigation](#). Wireless network signals can also be used for approximate positioning. When the application is started, the system loads the available visual data packets. The user takes a photo of their surroundings. The program then compares it with the database images in a fraction of a second and reveals the user's exact position. There is a snag, however, in that buildings are constantly changing: Signs are sometimes removed and large buildings will have construction work going on from time to time. Georg Schroth explains how NAVVIS stays up to date: "The system doesn't just position the user, it also utilizes the user's photos to record changes in the interior and overwrite obsolete data."



Realistic 3D reconstruction of a hallway at Technische Universität München.
Credit: G. Schroth/TUM

The TUM researchers are using a mapping trolley to map buildings. The trolley includes two laser scanners, single lens reflex cameras and a 360 degree camera. When the trolley passes along a corridor, the two lasers scan the dimensions horizontally and vertically and create a virtual map using three-dimensional point clouds. Software is then used to lay the photos over the pixels. This produces a realistic three-dimensional view.

Provided by Technical University Munich

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