

Virginia Tech robotics team dominates international RoboCup competition

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CHARLI 2 publicly debuted at the RoboCup 2011 competition in Istanbul, Turkey, and won the competition and main trophy of the event, the Louis Vuitton Humanoid Cup. CHARLI does not have hands yet. They are under development.

(PhysOrg.com) -- Virginia Tech's Robotics and Mechanisms Laboratory team dominated the international robot soccer competition known as RoboCup this past weekend, winning the Louis Vuitton Humanoid Cup, the competition's version of the Federation Internationale de Football Association's World Cup.

The team also dominated with First Place in both the Adult Size class with the 5-foot humanoid robot CHARLI-2 and the Kid Size class with the miniature-humanoid-robot DARwIn-OP.

The win is not just a first for College of Engineering team headed by Dennis Hong, associate professor of mechanical engineering, but a first for the United States. “Considered as the most prestigious award for humanoid robots, the Louis Vuitton Humanoid Cup is a beautiful crystal trophy and will be coming to the United States for the very first time,” Hong said via email from Istanbul, Turkey, where the RoboCup 20011 Tournament was hosted. “Since 2002, it has been in Japan for seven years, then Germany took it and had it for two years, and finally the United States -- Team CHARLI from Virginia Tech -- brings it home.”

In all Virginia Tech’s team took home four major awards from the international competition that is considered one of the most respected competitions in the robotics research community, and proposes a soccer match between full-size humanoid robots against the human World Cup human champions -- and win -- by the year 2050. Awards won include Best Humanoid Award, Louis Vuitton Humanoid Cup; First Place, Adult Size class; and Third Place, Technical Challenges for TEAM CHARLI, and First Place, Kid Size Class for TEAM DARwIn.

CHARLI 2 (that’s for Cognitive Humanoid Autonomous Robot with Learning Intelligence) is the second in a series of adult-sized, autonomous humanoid robots build at Virginia Tech. The first version, known as CHARLI-L (the "L" is for lightweight) debuted in spring 2010, and made national headlines, appearing on the cover of Popular Science and in Robot magazine. Both generations were designed and build by doctoral student Jeakweon Han, a native of Korea now living in Blacksburg. It is Han, who can be seen in YouTube videos on the Internet, standing behind CHARLI 2 as he takes the soccer court, scoring against various competitors. “Today is such a big day. CHARLI

won the final game and will bring Louis Vuitton Cup to Virginia Tech as the best humanoid,” said Han on his Facebook page, shortly after CHARLI won the final game in its division.

In the Kid Size Class, Team DARwIn beat several teams, including a team from Japan for the championship. Joining Virginia Tech’s Robotics and Mechanisms Laboratory was a team of engineering students from the University of Pennsylvania, who are collaborating with Hong’s group on [RoboCup](#) competitions involving the Kid Class humanoid robots and the development of DARwIn-OP.

Under director and founder Hong, the Robotics and Mechanisms Laboratory started project DARwIn (that’s Dynamic Anthropomorphic Robot with Intelligent) in 2003 to study human locomotion and humanoid robot design. DARwIn 1 was introduced in 2004 and was a revolutionary humanoid robot prototype at the time, and was followed by several incarnations since. DARwIn-OP was introduced this past year and is a fully open source design -- both software and hardware. All info on the hardware is to be shared on-line for free, including detailed plans and drawings, manuals for fabrication and assembly.

The Robotics and Mechanisms Laboratory will retain the Louis Vuitton [Humanoid](#) Cup until July 2012, when the next tournament kicks off in 2012.

Provided by Virginia Polytechnic Institute and State University

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